

## A Theorem of Hunt for Semidynamical Systems

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**Abstract:** The main result of this paper provides a direct proof of a Hunt's Theorem of the classical potential theory for the so called local semidynamical systems in non locally compact infinite dimensional spaces.

**Key words:** Excessive Functions, Hitting Time, Reduite Operator, Semidynamical System

### INTRODUCTION

The structure of this paper is adapted to the classical results which present a difficulty for the measurability. Starting by a transient semidynamical system  $(X, \mathcal{B}, \Phi, \omega)$ , [1-4], we introduce the notion of hitting time  $T_A$  of a measurable subset  $A$  of  $X_0$ . We prove the measurability of  $T_A$  with respect to the  $\sigma$ -algebra  $\mathcal{B}_0(\Lambda)$  defined in [5] and we give further properties by using the semidynamical specificity. We give a relationship between the hitting time  $T_A$  and the reduite operator  $R^A$  in classical potential theory and we give a direct proof of a Hunt's Theorem [6]. Here we don't use the Choquet capacity [7, 8]. However in the work of Hunt [6] cited here by as principal reference, the measurability is ensured with respect to the initial  $\sigma$ -algebra, but in this work, we express the measurability in a weak sense i.e. the measurability along the trajectories. Which is sufficient for integrate with respect to the reference Lebesgue measure  $\Lambda$ .

**Preliminary:** Here, we will introduce some definitions which will be useful in the remainder of this study [1, 4, 5, 9].

**Definition 1:** Let  $(X, \mathcal{B})$  be a separable measurable space with a distinguished point  $\omega$  and a measurable map  $\Phi: R_+ \times X \rightarrow X$  having the following properties:

(S<sub>1</sub>) for any  $x \in X$  there exists an element  $\rho(x) \in [0, +\infty]$  such that  $\Phi(t, x) \neq \omega$  for all  $t \in [0, \rho(x)[$  and  $\Phi(t, x) = \omega$  for all  $t \geq \rho(x)$ ,

(S<sub>2</sub>) for any  $s, t \in R_+$  and any  $x \in X$  we have

$$\Phi(s, \Phi(t, x)) = \Phi(s + t, x),$$

(S<sub>3</sub>)  $\Phi(0, x) = x$ , for all  $x \in X$ ,

(S<sub>4</sub>) if  $\Phi(t, x) = \Phi(t, y)$ , for all  $t > 0$ , then  $x = y$ .

The collection  $(X, \mathcal{B}, \Phi, \omega)$  is called semidynamical system with a coffin state  $\omega$ .

Set  $X_0 = X \setminus \{\omega\}$ . For any  $x \in X_0$  we denote by  $\Gamma_x$  the trajectory of  $x$ , i.e.:

$\Gamma_x = \{\Phi(t, x), t \in [0, \rho(x)]\}$  and we define the function  $\Phi_x$  on  $[0, \rho(x)[$  by  $\Phi_x(t) = \Phi(t, x)$ . So

for any  $x, y \in X_0$  we put  $x \leq_{\Phi} y$  if  $y \in \Gamma_x$ . A maximal trajectory is a totally ordered subset  $\Gamma$  of  $X_0$  with respect to the above order, such that there is no  $x_0 \in X_0 \setminus \Gamma$  which is a minorant of  $\Gamma$  and such for any  $x \in \Gamma$ , we have  $\Gamma_x \subset \Gamma$ .

In what follows, we shall suppose that  $(X, \mathcal{B}, \Phi, \omega)$  is a transient semidynamical system [1, 3]. In [1] we have associated a proper and submarkovian resolvent  $\mathbf{V} = (V_\alpha)_{\alpha \geq 0}$  of kernels on the measurable space  $(X_0, \mathcal{B}_0)$ , defined by :

$$V_\alpha f(x) = \int_0^{\rho(x)} e^{-\alpha t} f(\Phi(t, x)) dt, \forall x \in X_0, \forall \alpha \in R_+,$$

where,  $\mathcal{B}_0 = \{U \subset \mathcal{B}; U \subset X_0\}$ .

The family  $\mathbf{V}$  is the resolvent associated to the deterministic semigroup  $\mathbf{H} = (H_t)_{t \geq 0}$  introduced in [10, 11].

It is proved that the map  $\Phi_x$  is a measurable isomorphism between  $[0, \rho(x)[$  and  $\Gamma_x$  endowed with trace measurable structures.

Let  $\Lambda$  be the Lebesgue measure associated with the semidynamical system  $(X, \mathcal{B}, \Phi, \omega)$  [9] given by  $\Lambda(A) = \lambda(\Phi_x^{-1}(A))$  for any  $x \in X_0, A \in \mathcal{B}_0$  and  $A \subset \Gamma_x$ , where  $\lambda$  denotes the Lebesgue measure on  $R$ . We recall [5] that in the same way  $\Lambda$  can be defined on the  $\sigma$ -algebra  $\mathcal{B}_0(\Lambda)$  the set of all subsets  $A$  of  $X_0$  such that  $A \cap M \in \mathcal{B}_0$  for any countable union  $M$  of trajectories of  $X_0$ . Set  $\mathcal{B}_0^\sigma$  the collection of all countable union of trajectories of  $X_0$ . We denote by  $\mathbf{F}(X_0, \Lambda)$ , the set of all nonnegative  $\mathcal{B}_0(\Lambda)$ -measurable functions on  $X_0$ . One can show that the resolvent family  $\mathbf{V}$  may be considered on the measurable space  $(X_0, \mathcal{B}_0(\Lambda))$  by setting also :

$$V_\alpha f(x) = \int_0^{\rho(x)} e^{-\alpha t} f(\Phi(t, x)) dt, \forall x \in X_0, \forall \alpha \in R_+.$$

We consider also the arrival time function  $\Psi : X_0 \times X_0 \rightarrow R_+$ , given [2] by :

$$\Psi(x, y) = t \quad \text{if } \Phi(t, x) = y, t \in [0, \rho(x)[ \quad \text{and} \\ \Psi(x, y) = +\infty \quad \text{if not.}$$

It is shown that the arrival time function  $\Psi$  is measurable if we endow  $X_0 \times X_0$  with the product measurable structure of the  $\sigma$ -algebra  $\mathcal{B}_0(\Lambda)$  [5, 9]. Using the Lebesgue measure  $\Lambda$  and the function  $\Psi$ , we associate to the semidynamical system a dual resolvent  $\mathbf{V}^* = (V_\alpha^*)_{\alpha \geq 0}$  of kernels on the measurable space  $(X_0, \mathcal{B}_0(\Lambda))$  with respect to  $\Lambda$ , [5]. The above resolvent is given on  $\mathbf{F}(X_0, \Lambda)$  by:

$$V_\alpha^* f(x) = \int e^{-\alpha \Psi(y, x)} G(y, x) f(y) d\Lambda(y), \forall x \in X_0, \forall \alpha \in R_+,$$

where,  $G(y, x) = 1$ , if  $y \leq_\Phi x$  and  $G(y, x) = 0$ , if not, define the Green function associated to  $(X, \mathcal{B}, \Phi, \omega)$ .

For each  $x \in X_0$ , let us denote by:

$$\nu_x = \{v \subset X_0 : \exists \alpha \in ]0, \rho(x)[ / \Phi(t, x) \in v, \forall t \in [0, \alpha[ \}$$

and let  $\tau_\Phi$  be the topology for which  $\nu_x$  generates all the neighborhoods of  $x$  [1].  $\tau_\Phi$  is namely the fine topology associated with  $(X, \mathcal{B}, \Phi, \omega)$ .

Also denote by  $\tau_\Phi^0$  the inherent topology [1] associated with  $(X, \mathcal{B}, \Phi, \omega)$  which is characterized as being the set of all subset  $D$  of  $X_0$  having the following property:

$$\forall x \in X_0, \forall t_0 \in [0, \rho(x)[ : \Phi(t_0, x) \in D \Rightarrow \\ \Phi(t, x) \in D, \forall t \in ]t_0 - \varepsilon, t_0 + \varepsilon[ \cap [0, \rho(x)[, \\ \text{for some } \varepsilon > 0.$$

**Theorem 1:** The set  $\mathbf{E}(\Lambda)$  of the  $\mathbf{V}$ -excessive functions on  $(X_0, \mathcal{B}_0(\Lambda))$  is identical to the set of all positive decreasing functions on  $X_0$  with respect to the order ' $\leq_\Phi$ ', continuous with respect to the fine topology  $\tau_\Phi$  and finite at the points  $x \in X_0$  which are not minimal with respect to the same order [12]. Thus, the following result holds:

**Proposition 1:** Any function  $f \in \mathbf{E}(\Lambda)$  is lower semicontinuous with respect to  $\tau_\Phi^0$ .

**Proof :** Since  $\mathbf{V}$  is a proper submarkovian resolvent on  $(X_0, \mathcal{B}_0(\Lambda))$ , then by Hunt's approximation theorem, [13] page 23, there exists a sequence  $(f_n)_n$  in  $\mathbf{F}(X_0, \Lambda)$  such that  $\sup_n V_0 f_n = f$ . Since  $V_0 f_n$  is continuous with respect to  $\tau_\Phi^0$  [1], then  $f$  is lower semicontinuous with respect to  $\tau_\Phi^0$ .

Next, we shall prove the following Theorem which will be needed later.

**Theorem 2:** The following properties hold:

- (i) Every  $\tau_\Phi$ -open set is  $\mathcal{B}_0(\Lambda)$ -measurable,
- (ii) Every monotonous function  $f$  with respect to ' $\leq_\Phi$ ' is  $\mathcal{B}_0(\Lambda)$ -measurable.

**Proof**

1. Let  $O \in \tau_\Phi$ . Using a result in [1],  $\Gamma_x \in \tau_\Phi$ , we get that  $O \cap \Gamma_x \in \tau_\Phi$  which means that  $\Phi_x^{-1}(O \cap \Gamma_x)$  is an open set with respect to the fine trace topology on  $[0, \rho(x)[$ . Thus, it is measurable with respect to the trace Borel  $\sigma$ -algebra. Using the fact that  $\Phi_x$  is a measurable isomorphism, we get that  $O \cap \Gamma_x \in \mathcal{B}_0$  and therefore  $O \cap \Gamma_x \in \mathcal{B}_0(\Lambda)$ .
2. The function  $g$  defined by  $g(t) = f \circ \Phi(t, x) = f \circ \Phi_x(t)$  is monotonous on  $[0, \rho(x)[$  which is measurable with respect to trace Borel  $\sigma$ -algebra on  $[0, \rho(x)[$ . Using the fact that  $\Phi_x$  is a measurable isomorphism, we get that

$f = g \circ \Phi_x^{-1}$  is  $B_0$ -measurable and then  $f$  is  $B_0(\Lambda)$ -measurable.

In the sequel, for any subset  $A$  of  $X_0$  we put  $A^c := X_0 \setminus A$ .

**On the Measurability of the Hitting Time:** Blumenthal and Gettoor [7] proved the measurability of the hitting time for any Borel measurable subset  $A$  in the case of locally compact separable metric space.

**Proposition 2:** Let  $T$  be a positive measurable function on  $X$  with respect to the  $\sigma$ -algebra  $B$  ( respectively  $B(\Lambda)$  ), then the map  $\Phi_T$ , given by  $\Phi_T(x) = \Phi(T(x), x)$  if  $T(x) < \rho(x)$  and  $\Phi_T(x) = \omega$  if not, is measurable with respect to  $B$  ( respectively  $B(\Lambda)$  ).

**Proof:** The map  $U$  given on  $X$  by  $U(x) = (T(x), x)$  is measurable on  $X$  with respect  $B$  ( respectively  $B(\Lambda)$  ) and the product measurable structure. Then  $\Phi_T = \Phi \circ U$  is also measurable on  $X$  with respect to  $B$  ( respectively  $B(\Lambda)$  ).

**Notation:** For any positive function  $f$  defined on  $X_0$ , we put:

$$f(\Phi_T)(x) = f(\Phi_T(x)) \text{ if } T(x) < \rho(x) \text{ and } f(\Phi_T)(x) = 0 \text{ if not.}$$

**Definition 2:** Let  $A \in B(\Lambda)$  and for all  $x \in X$  we put  $D_A(x) = \inf\{t \geq 0 : \Phi(t, x) \in A\}$  if there exists and  $D_A(x) = +\infty$  if not.

Also we put  $T_A(x) = \inf\{t > 0 : \Phi(t, x) \in A\}$  if there exists and  $T_A(x) = +\infty$  if not.

The function  $D_A$  ( respectively  $T_A$  ) is called the first entry time ( respectively the first hitting time ) of  $A$ .

Note that, for any  $A \in B_0(\Lambda)$ , if  $D_A(x) \geq \rho(x)$  ( respectively  $T_A(x) \geq \rho(x)$  ), then

$$D_A(x) = T_A(x) = +\infty.$$

**Example:** The life time  $\rho$  is the first entry time or also the first hitting time in  $\{\omega\}$ .

Note that  $D_A(x) = 0$ , for any  $x \in A$ .

**Definition 3:** Let  $A \in B(\Lambda)$ . A point  $x$  is called regular for  $A$  if  $T_A(x) = 0$  and it is irregular if  $T_A(x) > 0$ . We denote by  $A^r$  the set of all regular points of  $A$ , i.e.  $A^r = [T_A = 0]$ .

**Remark 1:** Let  $A \in B_0(\Lambda)$  and denote by  $\overset{\circ}{A}$  the fine interior of  $A$  and by  $\bar{A}$  the set of all adherent points with respect to the fine topology  $\tau_\Phi$ . Then

$$\overset{\circ}{A} \subset A^r \subset \bar{A}.$$

**Proposition 3:** Let  $A \in B$  ( respectively  $B(\Lambda)$  ). The following properties hold:

- (i)  $s + D_A(\Phi(s, x)) = \inf\{t \geq s : \Phi(t, x) \in A\}$ ,
- (ii)  $s + T_A(\Phi(s, x)) = \inf\{t > s : \Phi(t, x) \in A\}$ ,
- (iii)  $t + D_A(\Phi(t, x)) = D_A(x)$  on the set  $[D_A \geq t]$ ,
- (iv)  $t + T_A(\Phi(t, x)) = T_A(x)$  on the set  $[T_A > t]$ ,
- (v)  $D_A \leq T_A$  and  $D_A = T_A$  if  $x \notin A$ .

**Corollary 1:** Let  $A \in B_0(\Lambda)$ . The following properties hold:

- (i)  $t + D_A(\Phi(t, x)) \geq D_A(x)$ ,
- (ii)  $t + T_A(\Phi(t, x)) \geq T_A(x)$ ,
- (iii)  $D_A$  is continuous with respect to the fine topology  $\tau_\Phi$  on each point of the set  $[D_A > 0]$ .
- (iv)  $T_A$  is continuous with respect to the fine topology  $\tau_\Phi$  on each point of the set  $[T_A > 0]$ .

**Proof**

(i) and (ii) are obvious by using (i) and (ii) in the last Proposition.

(iii) Let  $x \in X_0$  be such that  $D_A(x) > 0$ . Then, there exists  $0 < \alpha < D_A(x)$  and therefore  $D_A(x) > t$  for any  $t \in [0, \alpha]$ . Using the last Proposition, we conclude that

$$t + D_A(\Phi(t, x)) = D_A(x), \text{ for any } t \in [0, \alpha] \text{ and that } \lim_{t \rightarrow 0} D_A(\Phi(t, x)) = D_A(x) \text{ i.e. } D_A \text{ is continuous with}$$

respect to  $\tau_\Phi$  on the set  $[D_A > 0]$ .

In the same way we prove (iv).

**Proposition 4:** Let  $A$  be an open subset of  $X_0$  with respect to  $\tau_\Phi$ . Then  $D_A(x) = T_A(x)$  on  $X_0$  [7]. Moreover  $D_A$  is continuous with respect to the fine topology  $\tau_\Phi$ . Particularly,  $D_A$  is measurable with respect  $B_0(\Lambda)$ .

**Proof:** Since  $D_A \leq T_A$ , then  $D_A = 0$  if  $T_A = 0$ . Now, if  $T_A(x) > 0$  for some  $x \in X_0$ , then  $x \notin A$  and  $D_A(x) = T_A(x)$ . In fact, if  $x \in A$ , there exists  $\varepsilon > 0$  such that  $\Phi(t, x) \in A$ , for all  $t \in [0, \varepsilon[$  and therefore  $T_A(x) = 0$ .

Now, let  $x \in X_0$  be such that  $D_A(x) = 0$  i.e.  $T_A(x) = 0$  and there exists a non increasing sequence  $(t_n)_n \in (\mathbb{R}_+^*)^N$  such that  $\Phi(t_n, x) \in A$  and  $\lim_{n \rightarrow +\infty} t_n = 0$ . So, for any  $\varepsilon > 0$ , there exists  $n_0$  such that  $t_{n_0} < \varepsilon$  and therefore  $D_A(\Phi(t, x)) \leq t_{n_0} - t < \varepsilon, \forall t \in [0, t_{n_0}]$ . So that  $D_A$  is continuous at  $x$  with respect to the fine topology  $\tau_\Phi$ . The proof then holds by Corollary 1.

**Proposition 5:** Let  $A, B \in \mathcal{B}_0(\Lambda)$ . Then, the following assertions hold [7]:

- (i)  $A \subset B \Rightarrow D_B \leq D_A$  and  $T_B \leq T_A$ ,
- (ii)  $D_{A \cup B} = \inf\{D_A, D_B\}$  and  $T_{A \cup B} = \inf\{T_A, T_B\}$ ,
- (iii)  $\sup\{D_A, D_B\} \leq D_{A \cap B}$  and  $\sup\{T_A, T_B\} \leq T_{A \cap B}$ ,
- (iv) for any increasing sequence  $(A_n)_n$  of measurable subsets of  $X_0$  such that  $A = \bigcap_n A_n$ , we have

$$D_A = \inf_n D_{A_n} \text{ and } T_A = \inf_n T_{A_n}.$$

In the sequel set  $x < y$  for any  $x, y \in X_0$  such that  $x \leq_\Phi y$  with  $x \neq y$  and set:

- 1.  $]x, y[ = \{z \in X_0 : x \leq_\Phi z \leq_\Phi y\}$ ,
- 2.  $]x, y[ = \{z \in X_0 : x \leq_\Phi z < y\}$ ,
- 3.  $]x, y[ = \{z \in X_0 : x < z < y\}$ ,
- 4.  $]x, y[ = \{z \in X_0 : x < z \leq_\Phi y\}$ .

**Proposition 6 :** Let  $A$  be a closed subset of  $X_0$  with respect to  $\tau_\Phi$ . Then,  $T_A$  is continuous with respect to  $\tau_\Phi$ .

**Proof:** Let  $x_0 \in X_0$  be such that  $T_A(x_0) < +\infty$  (obviously that  $T_A(x_0) = +\infty \Rightarrow T_A(x) = +\infty, \forall x \in \Gamma_{x_0}$ ).

**First Case:** If  $x_0 \in X_0 \setminus A$ , then there exists  $\varepsilon > 0$  such that  $]x_0, \Phi(\varepsilon, x_0)[ \subset X_0 \setminus A$  and so  $T_A(x_0) > \Psi(x_0, x), \forall x \in ]x_0, \Phi(\varepsilon, x_0)[$ . Then,  $T_A(x_0) = T_A(x) + \Psi(x_0, x)$  and  $0 \leq T_A(x_0) - T_A(x) < \varepsilon, \forall x \in ]x_0, \Phi(\varepsilon, x_0)[$ .

**Second Case:** If  $x_0 \in A$ , then there exists  $\varepsilon > 0$  such that  $]x_0, \Phi(\varepsilon, x_0)[ \subset A$  and so  $T_A(x) = 0, \forall x \in ]x_0, \Phi(\varepsilon, x_0)[$ .

**Third Case:** If  $x_0 \in \overset{\circ}{\partial}A = A \setminus A$ , then for any  $\varepsilon > 0$  there exists  $b \in ]x_0, \Phi(\varepsilon, x_0)[ \cap (X_0 \setminus A)$ . If there exists  $\varepsilon > 0$  such that  $]x_0, \Phi(\varepsilon, x_0)[ \cap A = \emptyset$ , so  $T_A(x_0) > \Psi(x_0, x)$  and  $T_A(x_0) = T_A(x) + \Psi(x_0, x), \forall x \in ]x_0, \Phi(\varepsilon, x_0)[$ .

Then, for any  $x \in ]x_0, \Phi(\varepsilon, x_0)[$ , we have  $0 \leq T_A(x_0) - T_A(x) < \varepsilon$ . Finally, suppose that for any  $\varepsilon > 0$  there exists  $a \in ]x_0, \Phi(\varepsilon, x_0)[ \cap A$  and therefore for  $\alpha = \Psi(x_0, a)$ , we have  $T_A(x) \leq \Psi(x_0, a) < \varepsilon, \forall x \in ]x_0, \Phi(\alpha, x_0)[$ .

In particular,  $T_A(x_0) = 0$  and for any  $x \in ]x_0, \Phi(\alpha, x_0)[, 0 \leq T_A(x) - T_A(x_0) < \varepsilon$ .

In the different cases cited above, we conclude that  $T$  is continuous at  $x_0$  with respect to  $\tau_\Phi$ .

**Remark 2:** In the proof given above we can deduce that  $T_A$  is continuous at  $x_0$  in the first and the third case by using Corollary 1.

**Theorem 3:** For any  $A \in \mathcal{B}_0(\Lambda)$ , we have the following assertions:

- (i)  $D_A = D_A^-$  and  $T_A = T_A^-$ ,
- (ii)  $D_A$  ( $T_A$  resp.) is lower semicontinuous (continuous resp.) with respect to the fine topology  $\tau_\Phi$ .
- (iii)  $D_A$  and  $T_A$  are measurable on  $X_0$  with respect to  $\mathcal{B}_0(\Lambda)$ .

**Proof**

- (i) Obviously,  $D_A^- \leq D_A$  and  $T_A^- \leq T_A$  (Proposition 5). Next, let  $x \in X_0$  be such that  $D_A^-(x) < +\infty$  ( $T_A^-(x) < +\infty$  resp.) and

let  $t \geq 0$  ( $t > 0$  resp.) be such that  $\Phi(t, x) \in A$ . By using Proposition 3 in [1] we deduce that for any  $n \in \mathbb{N}^*$  there exists  $t_n \in [0, \frac{1}{n}]$  such that  $\Phi(t + t_n, x) \in A$  and therefore

$$D_A(x) \leq t + t_n \leq t + \frac{1}{n} \text{ (} T_A(x) \leq t + t_n \leq t + \frac{1}{n} \text{ resp.)}$$

$$\text{Hence, } D_A(x) \leq D_A^-(x) + \frac{1}{n}$$

(  $T_A(x) \leq T_A^-(x) + \frac{1}{n}$  resp. ), for any  $n \in \mathbb{N}^*$ .  
 Consequently  $D_A(x) \leq D_A^-(x)$  (  $T_A(x) \leq T_A^-(x)$  resp. ). Note that if  $D_A^-(x) = +\infty$  (  $T_A^-(x) = +\infty$  resp. ), then  $D_A(x) = +\infty$  (  $T_A(x) = +\infty$  resp. ).  
 (ii) Let  $\alpha \geq 0$  and let  $(x_n)_n$  be a sequence in  $[D_A(x) \leq \alpha]$  which converges to  $x_0 \in X_0$  with respect to  $\tau_\Phi$ . If  $D_A(x_0) = 0$ , then  $x_0 \in [D_A(x) \leq \alpha]$ . If  $D_A(x_0) > 0$ , then by Corollary 1  $D_A$  is continuous at  $x_0$  w.r. to  $\tau_\Phi$ . So that  $(D_A(x_n))_n$  converges to  $D_A(x_0)$  and therefore  $x_0 \in [D_A(x) \leq \alpha]$ . By Proposition 6 we get that  $T_A$  is continuous with respect to  $\tau_\Phi$ .  
 (iii) It is obvious by (ii).

**Proposition 7:** Let  $A \in \mathbf{B}_0(\Lambda)$ . So, we have  $D_A = \inf \{ D_{A \cap M}, M \in \mathbf{B}_0(\Lambda) \}$  and  $T_A = \inf \{ T_{A \cap M}, M \in \mathbf{B}_0(\Lambda) \}$ .

**Proof:** Obviously, for any  $M \in \mathbf{B}_0(\Lambda)$ , we have  $D_A \leq D_{A \cap M}$  and  $T_A \leq T_{A \cap M}$ .  
 Next, we denote by  $\mathbf{B}_0^\sigma$  the set of all countable unions of trajectories of  $X_0$  and let  $x_0 \in X_0$  such that  $D_A(x_0) < \alpha$  (respectively  $T_A(x_0) < \alpha$ ) for some real number  $\alpha$ . Then, there exists  $t \in ]0, \alpha[$  (respectively  $t \in ]0, \alpha[$ ) such that  $\Phi(t, x_0) \in A$ . But  $A = \bigcup_M A \cap M$ , where  $M$  rains the  $\sigma$ -algebra  $\mathbf{B}_0^\sigma$ , so there exists  $M_0 \in \mathbf{B}_0^\sigma$  such that  $\Phi(t, x_0) \in A \cap M_0$  so that  $D_{A \cap M_0}(x_0) < \alpha$  (respectively  $T_{A \cap M_0}(x_0) < \alpha$ ).

Then, we have  $D_A(x_0) = \inf \{ D_{A \cap M}(x_0), M \in \mathbf{B}_0(\Lambda) \}$  and  $T_A(x_0) = \inf \{ T_{A \cap M}(x_0), M \in \mathbf{B}_0(\Lambda) \}$ .

**Remark 3:** Notice that for any  $A \in \mathbf{B}_0(\Lambda)$  and any  $x_0 \in X_0$  we have  $x \leq_\Phi \Phi_{D_A}(x)$  and  $x \leq_\Phi \Phi_{T_A}(x)$ .

**Notation:** For any  $x, y \in X_0$  we write  $x < y$  if  $x \leq_\Phi y$  and  $x \neq y$ .

**Proposition 8:** Let  $A \in \mathbf{B}_0(\Lambda)$ . Then, the following properties hold:

(i) The maps  $\Phi_{D_A}$  and  $\Phi_{T_A}$  are increasing, in particular  $\Phi_{D_A}$  and  $\Phi_{T_A}$  are measurable on  $X_0$  with respect to  $\mathbf{B}_0(\Lambda)$ .

(ii)  $\forall x_1, x_2 \in X_0, x_1 < x_2$  we have  $\Phi_{D_A}(x_1) = \Phi_{D_A}(x_2) \Leftrightarrow [x_1, x_2[ \cap A = \emptyset$  (respectively

$$\Phi_{T_A}(x_1) = \Phi_{T_A}(x_2) \Rightarrow [x_1, x_2[ \cap \overset{0}{A} = \emptyset),$$

(iii) If  $A$  is dense in  $X_0$  with respect to  $\tau_\Phi$ , then  $D_A = T_A = 0$  and for any  $x_1, x_2 \in X_0$  we have  $x_1 < x_2 \Rightarrow \Phi_{D_A}(x_1) = \Phi_{D_A}(x_2)$ .

**Proof**

(i) Let  $x_1, x_2 \in X_0, x_1 < x_2$ . Then we obtain  $D_A(x_1) \leq D_A(x_2) + \Psi(x_1, x_2)$  and  $T_A(x_1) \leq T_A(x_2) + \Psi(x_1, x_2)$  (Corollary 1).

Also we deduce that  $\Phi_{D_A}(x_1) \leq_\Phi \Phi_{D_A}(x_2)$  and  $\Phi_{T_A}(x_1) \leq_\Phi \Phi_{T_A}(x_2)$ .

(ii) Let  $x_1, x_2 \in X_0, x_1 < x_2$  be such that  $[x_1, x_2[ \cap A \neq \emptyset$  and let  $a \in [x_1, x_2[ \cap A$ . Then, we have

$$D_A(x_1) \leq \Psi(x_1, a) < \Psi(x_1, x_2).$$

Therefore we get  $\Phi_{D_A}(x_1) < \Phi(\Psi(x_1, x_2), x_1)$ ,

i.e.  $\Phi_{D_A}(x_1) < x_2 \leq_\Phi \Phi_{D_A}(x_2)$ .

Conversely, if  $[x_1, x_2[ \cap A = \emptyset$ , we get

$D_A(x_1) = D_A(x_2) = +\infty$  or there exists  $a_0 \in A$  such that  $x_1 < x_2 < a_0$  and therefore

$\Phi_{D_A}(x_1) = \Phi_{D_A}(x_2) = \wedge \{ a \in A : x_2 < a \}$ , the infimum with respect to the associated order.

Now let  $a \in [x_1, x_2[ \cap \overset{0}{A}$ , so there exists  $\varepsilon > 0$  such that  $[a, \Phi(\varepsilon, a)[ \subset [x_1, x_2[ \cap \overset{0}{A}$ . We consider  $a_1 \in ]a, \Phi(\varepsilon, a)[$  and therefore

$$T_A(x_1) \leq \Psi(x_1, a_1) < \Psi(x_1, x_2).$$

Then,  $\Phi_{T_A}(x_1) < x_2 \leq_\Phi \Phi_{T_A}(x_2)$ .

(iii) Suppose that  $A$  is a dense subset of  $X_0$  with respect to  $\tau_\Phi$ .

So for any  $x \in X_0$  and any  $n \in \mathbb{N}^* \cap \left] \frac{1}{\rho(x)}, +\infty \right[$ ,

there exists  $x_n \in A \cap [x, \Phi(\frac{1}{n}, x)[$  and therefore

$$D_A(x) \leq T_A(x) = 0.$$

**Proposition 9:** Let  $A \in \mathbf{B}_0(\Lambda)$ . Then for any  $x \in X_0$  such that  $D_A(x) < +\infty$  (respectively  $T_A(x) < +\infty$ ) we have  $\Phi_{D_A}(x) \in \bar{A}$  (respectively  $\Phi_{T_A}(x) \in \bar{A}$ ).

**Proof:** For any  $x \in X_0$  such that  $D_A(x) < +\infty$  (respectively  $T_A(x) < +\infty$ ) there exists a decreasing sequence  $(t_n)_n$  of positive real numbers such that  $D_A(x) = \lim_n t_n$  (respectively  $T_A(x) = \lim_n t_n$ ) and for any  $n$ ,  $\Phi(t_n, x) \in A$ . Since  $t \mapsto \Phi(t, x)$  is a right continuous map with respect to  $\tau_\Phi$ , then we have  $\Phi_{D_A}(x) \in \bar{A}$  (respectively  $\Phi_{T_A}(x) \in \bar{A}$ ).

**Corollary 2:** Let  $A$  be a closed subset of  $X_0$  with respect to  $\tau_\Phi$ . Then, for any  $x \in X_0$  such that  $D_A(x) < +\infty$  (respectively  $T_A(x) < +\infty$ ) we have  $\Phi_{D_A}(x) \in A$  (respectively  $\Phi_{T_A}(x) \in A$ ).

**Remark 4:** Let  $A \in \mathbf{B}_0(\Lambda)$  and  $x \in \overset{0}{A}$ . Then  $T_A(x) = 0$ .

**Proof:** Let  $x \in \overset{0}{A}$ , then there exists  $\mathcal{E} > 0$  such that  $[x, \Phi(\mathcal{E}, x)[ \subset A$  and therefore  $T_A(x) = 0$ .

**A Hunt Theorem for Semidynamical Systems:** In this section  $\mathbf{S}$  (respectively  $\mathbf{E}$ ) will simply denote the set of all supermedian (respectively excessive) functions with respect to the extension resolvent  $\mathbf{V}$ .

**Definition 4:** Let  $A \in \mathbf{B}_0(\Lambda)$  and let  $s \in \mathbf{E}$ . The map  ${}^s R_s^A$  (respectively  $R_s^A$ ) given on  $X_0$  by, the pointwise infimum [13],  ${}^s R_s^A := \inf \{t \in \mathbf{S} : t \geq s \text{ on } A\}$  (respectively  $R_s^A := \inf \{t \in \mathbf{E} : t \geq s \text{ on } A\}$ ) is called the reduite of  $s$  on  $A$  with respect to  $\mathbf{S}$  (respectively  $\mathbf{E}$ ).

**Definition 5:** For any  $A \in \mathbf{B}_0(\Lambda)$  and any  $s \in \mathbf{E}$  the map  $B_s^A$  given on  $X_0$  by [13]:  $B_s^A := \wedge \inf \{t \in \mathbf{E} : t \geq s \text{ on } A\}$ , where, the infimum is considered in  $\mathbf{E}$ , is called the balayage of  $s$  on  $A$ .

**Theorem 4:** Let  $A \in \mathbf{B}_0(\Lambda)$  and let  $s \in \mathbf{E}$ . Then, we have  $B_s^A = \overset{\wedge}{R_s^A} := \sup_{\alpha > 0} \alpha V_\alpha(R_s^A)$ ,

the excessive regularization. In particular

$$B_s^A = R_s^A \quad \Lambda - \text{a.e.}$$

**Proof:** Let  $(t_i)_{i \in I}$  be a family of all the elements of  $\mathbf{E}$  such that  $t_i \geq s$  on  $A$ . Then, we have  $R_s^A = \inf_{i \in I} t_i$

(Note that  $R_s^A$  is measurable with respect to  $\mathbf{B}_0(\Lambda)$  by Theorem 2) which is supermedian with respect to  $\mathbf{V}$  and  $\overset{\wedge}{R_s^A}$  is in  $\mathbf{E}$  and so  $\overset{\wedge}{R_s^A} = \wedge_{i \in I} t_i = B_s^A$ , where,  $\wedge_{i \in I} t_i$  is the greatest lower bound in  $\mathbf{E}$ .

The following result is due to Mokobodzki. For the proof one can see [13], pages 9 and 13.

**Proposition 10:** For any  $A \in \mathbf{B}_0(\Lambda)$  and any  $s \in \mathbf{S}$ , the function  ${}^s R_s^A$  is supermedian with respect to  $\mathbf{V}$ . For the following result also see [13].

**Proposition 11:** For any  $A \in \mathbf{B}_0(\Lambda)$  and any  $s \in \mathbf{E}$ , we have  $R_s^A = \overset{\bar{}}{R_s^A}$ .

**Proof:** It is obvious that  $R_s^A \leq \overset{\bar{}}{R_s^A}$ . Now, let  $t \in \mathbf{E}$  such that  $t \geq s$  on  $A$ . since  $s$  and  $t$  are continuous with respect to  $\tau_\Phi$ , we get  $t \geq s$  on  $\bar{A}$  and therefore  $t \geq s$  on  $\bar{A}$  which implies that  $R_s^A \geq \overset{\bar{}}{R_s^A}$ .

**Corollary 3:** For any  $A \in \mathbf{B}_0(\Lambda)$  and any  $s \in \mathbf{E}$ , we have  $s(\Phi_{T_A}) = R_s^A$ .

**Proof:** Let  $x \in X_0$  be such that  $T_A(x) < +\infty$  and let  $u \in \mathbf{E}$  be such that  $u \geq s$  on  $\bar{A}$ . Since by Proposition 9,  $\Phi_{T_A}(x) \in \bar{A}$ , then  $u(x) \geq u(\Phi_{T_A}(x)) \geq s(\Phi_{T_A}(x))$  and hence  $\overset{\bar{}}{R_s^A}(x) \geq s(\Phi_{T_A}(x))$ , which yields by Proposition 11 that  $\overset{\bar{}}{R_s^A} \geq s(\Phi_{T_A})$ .

Note that if  $T_A(x) = +\infty$ , then  $s(\Phi_{T_A}(x)) = 0$ .

**Theorem 5:** Let  $A$  be a closed subset of  $X_0$  with respect to  $\tau_\Phi$  and let  $s \in \mathbf{S}$ . Then, we have  ${}^s R_s^A = s(\Phi_{D_A})$ .

**Proof:** Since  $s(\Phi_{D_A})$  is a decreasing function (Proposition 8), then  $s(\Phi_{D_A}) \in \mathbf{S}$ . Moreover for any

$x \in A$  we have  $s(\Phi_{D_A}(x)) = s(x)$ . Now, let  $t \in \mathbf{S}$  such that  $t \geq s$  on  $A$ . Since  $A$  is closed with respect to  $\tau_\phi$ , then  $\Phi_{D_A}(x) \in A$  for any  $x \in X_0$  such that  $D_A(x) < +\infty$  and therefore  $t(x) \geq t(\Phi_{D_A}(x)) \geq s(\Phi_{D_A}(x))$ . Now, if  $D_A(x) = +\infty$ , then  $\Phi_{D_A}(x) = \omega$  and  $t(x) \geq s(\Phi_{D_A}(x)) = 0$ .

**Theorem 6:** Let  $A$  be a fine open subset of  $X_0$  and let  $s \in \mathbf{E}$ . Then, we have  $B_s^A = R_s^A = s(\Phi_{D_A})$ .

**Proof:** For any  $x \in X_0$  and  $t \in [0, \rho(x)[$ , we have  $\Phi_{D_A}(\Phi(t,x)) = \Phi(D_A(\Phi(t,x)), \Phi(t,x)) = \Phi(t+D_A(\Phi(t,x)), x)$ . But  $D_A$  is continuous with respect to  $\tau_\phi$  (Proposition 4), so  $\lim_{t \rightarrow 0^+} (t+D_A(\Phi(t,x))) = D_A(x)$  and therefore  $s(\Phi_{D_A})$  is continuous with respect to  $\tau_\phi$ . Since  $s(\Phi_{D_A})$  is a decreasing function and continuous with respect to the fine topology  $\tau_\phi$ , then  $s(\Phi_{D_A}) \in \mathbf{E}$ . Now, let  $t \in \mathbf{E}$  such that  $t \geq s$  on  $A$ . Since  $s$  and  $t$  are continuous with respect to the fine topology  $\tau_\phi$ , so  $t \geq s$  on  $\bar{A}$ . But for any  $x \in X_0$  such that  $D_A(x) < +\infty$ , we have that  $\Phi_{D_A}(x) \in \bar{A}$  and therefore  $t(x) \geq t(\Phi_{D_A}(x)) \geq s(\Phi_{D_A}(x))$ . Now, if  $D_A(x) = +\infty$ , then  $\Phi_{D_A}(x) = \omega$  and  $t(x) \geq s(\Phi_{D_A}(x)) = 0$ .

**Remark 5:** For the case of continuous semidynamical system on a locally compact space with countable base in [11] is proved the above statement for any complement of compact set.

**Theorem 7:** Let  $A \in \mathbf{B}_0(\Lambda)$  and  $s \in \mathbf{E}$ . Then, [13, 14] we have  $R_s^A = \inf \{R_s^G : G \in \tau_\phi, A \subset G\}$ .

**Proof:** Obviously,  $R_s^A \leq \inf \{R_s^G : G \in \tau_\phi, A \subset G\}$ . Now, let  $t \in \mathbf{E}$  be such that  $t \geq s$  on  $A$ . Then, for every  $\varepsilon > 0$  the subset  $G_\varepsilon = [t + \varepsilon > s]$  is a fine open subset which contains  $A$ . Since  $t + \varepsilon > s$  on  $G_\varepsilon$ , it follows that  $t + \varepsilon \geq R_s^{G_\varepsilon} \geq \inf \{R_s^G : G \in \tau_\phi, A \subset G\}$

and therefore  $t \geq \inf \{R_s^G : G \in \tau_\phi, A \subset G\}$ . Consequently  $R_s^A \geq \inf \{R_s^G : G \in \tau_\phi, A \subset G\}$ .

In the sequel we formulate and we give a direct proof of Hunt's fundamental Theorem which is proved in [6-8]. In our case, we don't assume that the state space  $X$  is a locally compact metric space with countable base.

**Theorem 8:** Let  $A \in \mathbf{B}_0(\Lambda)$  and  $s \in \mathbf{E}$ . Then  $s(\Phi_{T_A}) \leq R_s^A$  on  $X_0$  and  $s(\Phi_{T_A}) = R_s^A$  except on  $A \cap (A^r)^c$ .

**Proof:** By Corollary 3, we have that  $s(\Phi_{T_A}) \leq R_s^A$  for any  $A \in \mathbf{B}_0(\Lambda)$ . Next, let  $x \in A^r$  (i.e.  $T_A(x) = 0$ ). Since  $R_s^A \leq s$ , then  $s(\Phi_{T_A}(x)) \leq R_s^A(x) \leq s(x) = s(\Phi_{T_A}(x))$ . Hence  $s(\Phi_{T_A}) \leq R_s^A$  on  $A^r$ .

Now, let  $x \in A^c$  be such that  $T_A(x) = +\infty$ . It is obvious that  $T_A = D_A$  on  $A^c$  (see Proposition 3) and therefore  $D_A(x) = +\infty$ . Hence, we deduce that  $A \subset \Gamma_x^c$ . Since by Theorem 1,  $1_{\Gamma_x^c} \in \mathbf{E}$ , then  $s1_{\Gamma_x^c} \in \mathbf{E}$ .

On the other hand, using the fact that  $s1_{\Gamma_x^c} = s$  on  $A$ , we obtain  $R_s^A(x) = 0 = s(\Phi_{T_A}(x))$ .

Next, let  $x \in A^c \cap (A^r)^c$  be such that  $T_A(x) < +\infty$ , then the ordered interval  $U_x = [x, \Phi_{T_A}(x)[$  is a fine open and also a fine closed non empty subset of  $X_0$  (Proposition 4) in [1] and  $U_x \subset A^c$ . Let us set  $s_x = s(\Phi_{T_A})$  on  $U_x$  and  $s_x = s$  on  $(U_x)^c$ .

Obviously,  $s_x$  is continuous on  $U_x$  with respect to  $\tau_\phi$ . Also,  $s_x = s$  on  $(U_x)^c$  on the fine open subset  $(U_x)^c$  with respect to  $\tau_\phi$ . Since  $X_0 = U_x \cup (U_x)^c$  and

$U_x \cap (U_x)^c = \emptyset$ , we get that  $s_x$  is  $\tau_\phi$ -continuous. Using the fact that  $s_x$  is decreasing on  $X_0$ , we obtain by Theorem 1 that  $s_x \in \mathbf{E}$ . But the fact that  $A \subset U_x^c$  gives us that  $s_x = s$  on  $A$  and therefore  $R_s^A(x) \leq s_x$ . Particularly,  $R_s^A(x) \leq s(\Phi_{T_A}(x))$ . Hence

$R_s^A(x) = s(\Phi_{T_A}(x))$  and consequently  $R_s^A = s(\Phi_{T_A})$  on  $X_0 \setminus (A \cap (A^r)^c)$ .

**Remark 6:** In [1] it is proved the above statement for any  $A \in \mathbf{B}_0$  in the case where  $s = 1$  on  $X_0$ .

**Corollary 4:** Let  $A$  be a subset of  $X_0$  which is closed with respect to  $\tau_\Phi$  and such that  $\Lambda(A \setminus A^r) = 0$  and let  $s \in \mathbf{E}$ . Then, we have  $B_s^A = s(\Phi_{T_A})$ .

**Proof:** Since  $s(\Phi_{T_A})$  is a decreasing function and continuous with respect to  $\tau_\Phi$ , then, by Proposition 6 and Theorem 1,  $s(\Phi_{T_A}) \in \mathbf{E}$  [1, 12]. On the other hand, by Theorem 4:

$B_s^A = \hat{R}_s^A = R_s^A$ ,  $\Lambda$ -a.e. and  $R_s^A = s(\Phi_{T_A})$  except on  $A \setminus A^r$ , which is  $\Lambda$ -negligible. Then,  $B_s^A = s(\Phi_{T_A})$   $\Lambda$ -a.e. Since  $B_s^A$  and  $s(\Phi_{T_A}) \in \mathbf{E}$ , we get [5]

$$B_s^A = s(\Phi_{T_A}).$$

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