

## Reliability Parameters of a Power Generating System with Shared Load

<sup>1</sup>Ritu Gupta, <sup>2</sup>S.K. Mittal and <sup>1</sup>C.M. Batra

<sup>1</sup>Krishna Institute of Engineering and Technology, Ghaziabad, UP, India

<sup>2</sup>M.M. (PG) College, Modinagar, India

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**Abstract:** This study presents a model, based on power generating system with shared load. The whole generating system consists of three subsystems viz: subsystem A, subsystem B and subsystem C. The subsystem A consists of one generating unit and one inbuilt transformer. The subsystem B also contains the same units and is connected in parallel to subsystem A. The output of this power system goes through the subsystem C that consists of one outer transformer and which may be further distributed as desired. The system has three types of states, viz: normal, degraded and failed. All types of failure rates and repair rates of inbuilt transformers are exponential while other repair rates are distributed quite generally. Supplementary Variable Technique has been employed to obtain various state probabilities and then the reliability parameters have been evaluated for the whole generating system.

**Key words:** Reliability, availability, MTTF, SVT

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### INTRODUCTION

Electric energy demand has been rapidly increasing all over the world. This is attributed to greater industrialization and large-scale use of electric energy for agricultural purpose. The demand is likely to increase exponentially for many more decades to come. There are no signs of saturation in the foreseeable future. Electric supply authorities are likely to pay more attention to improve the utilization of generating equipment. The reliability of electric supply in India is very low. The public is likely to become more and more conscious of its rights to get uninterrupted supply at proper voltage. This would force the electric supply undertakings to analyze the system and take corrective measures to improve reliability.

Keeping these points in view, the author has considered a mathematical model by which the reliability of the generating system can be improved. The whole generating system consists of three subsystems viz, subsystem A, subsystem B and subsystem C. The subsystem A consists of one generating unit and one inbuilt transformer. The subsystem B, arranged in parallel with subsystem A, is a redundant system and also consists of one generating unit and one inbuilt transformer. The output of these two subsystems goes through the subsystem C that consists of one outer transformer and the electric supply may be further distributed from this subsystem C as desired. The power required at subsystem

C is shared by two subsystems, A and B which will increase the availability of power in comparison to that which is, instead, produced by a single subsystem A. Supplementary Variable technique has been employed to evaluate various reliability parameters of the generating system. The mathematical model of the whole system is shown in the state transition diagram.

### ASSUMPTIONS

- At time  $t = 0$ , the system is in operable state.
- The subsystem B works as the redundant unit.
- All the failure rates and repair rates of unit A2 and unit B2 (inbuilt transformers) are exponential while other repair rates are distributed quite generally.
- The failure rate of all units is distinct.
- After the complete breakdown of the system, the repair rate is assumed as same.
- The system is in degraded state after the failure of either unit of subsystem A or subsystem B, or completely subsystem A or subsystem B.
- All the units recover their functioning perfectly after repair.

**Formulation of the model:** The probabilities given above are mutually exclusive and provide the complete markovian characteristic of the process. Therefore, using continuity arguments and elementary probability considerations, one get the following difference

differential equations governing the stochastic behaviour of the complex system, which is discrete in space and continuous in time:

$$\left(\frac{d}{dt} + \lambda_a + \lambda_b + \lambda_1 + \lambda_2 + \lambda\right)P_1(t) = \int \mu_1(x)P_2(x,t)dx + \int \mu(z)P_4(z,t)dz + \int \mu_1(x)P_3(x,t)dx + \int \mu(z)P_8(z,t)dz + \int \mu(z)P_7(z,t)dz + \int \mu_2(y)P_6(y,t)dy + \int \mu(z)P_9(z,t)dz + vP_5(t) + vP_{11}(t) + \int \mu_2(y)P_{12}(y,t)dy + \int \mu(z)P_{10}(z,t)dz + \int \mu(z)P_{13}(z,t)dz + \int \mu(z)P_{14}(z,t)dz + \int \mu(z)P_{15}(z,t)dz + \int \mu(z)P_{16}(z,t)dz + \int \mu(z)P_{17}(z,t)dz \tag{1}$$

$$\left(\frac{\partial}{\partial x} + \frac{\partial}{\partial t} + \lambda + \lambda_b + \mu_1(x)\right)P_2(x,t) = 0 \tag{2}$$

$$\left(\frac{\partial}{\partial x} + \frac{\partial}{\partial t} + \lambda_a + \lambda + \mu_1(x)\right)P_3(x,t) = 0 \tag{3}$$

$$\left(\frac{\partial}{\partial z} + \frac{\partial}{\partial t} + \mu(z)\right)P_4(z,t) = 0 \tag{4}$$

$$\left(\frac{\partial}{\partial t} + v + \lambda_2 + \lambda_b + \lambda + \lambda_a\right)P_5(t) = \lambda_1 P_1(t) \tag{5}$$

$$\left(\frac{\partial}{\partial y} + \frac{\partial}{\partial t} + \lambda_b + \lambda_2 + \mu_2(y) + \lambda\right)P_6(y,t) = 0 \tag{6}$$

$$\left(\frac{\partial}{\partial z} + \frac{\partial}{\partial t} + \mu(z)\right)P_7(z,t) = 0 \tag{7}$$

$$\left(\frac{\partial}{\partial z} + \frac{\partial}{\partial t} + \mu(z)\right)P_8(z,t) = 0 \tag{8}$$

$$\left(\frac{\partial}{\partial z} + \frac{\partial}{\partial t} + \mu(z)\right)P_9(z,t) = 0 \tag{9}$$

$$\left(\frac{\partial}{\partial z} + \frac{\partial}{\partial t} + \mu(z)\right)P_{10}(z,t) = 0 \tag{10}$$

$$\left(\frac{d}{dt} + \lambda + \lambda_b + \lambda_a + \lambda_1 + v\right)P_{11}(x,t) = \lambda_2 P_1(t) \tag{11}$$

$$\left(\frac{\partial}{\partial y} + \frac{\partial}{\partial t} + \lambda_a + \lambda_1 + \mu_2(y) + \lambda\right)P_{12}(y,t) = 0 \tag{12}$$

$$\left(\frac{\partial}{\partial z} + \frac{\partial}{\partial t} + \mu(z)\right)P_{13}(z,t) = 0 \tag{13}$$

$$\left(\frac{\partial}{\partial z} + \frac{\partial}{\partial t} + \mu(z)\right)P_{14}(z,t) = 0 \tag{14}$$

$$\left(\frac{\partial}{\partial z} + \frac{\partial}{\partial t} + \mu(z)\right)P_{15}(z,t) = 0 \tag{15}$$

$$\left(\frac{\partial}{\partial z} + \frac{\partial}{\partial t} + \mu(z)\right)P_{16}(z,t) = 0 \tag{16}$$

$$\left(\frac{\partial}{\partial z} + \frac{\partial}{\partial t} + \mu(z)\right)P_{17}(z,t) = 0 \tag{17}$$

**Boundary conditions:**

$$P_2(0,t) = \lambda_a P_1(t) \tag{18}$$

$$P_3(0,t) = \lambda_b P_1(t) \tag{19}$$

$$P_4(0,t) = \lambda_a \int P_3(x,t)dx + \lambda_b \int P_2(x,t)dx \tag{20}$$

$$P_6(0,t) = \lambda_a P_5(t) \tag{21}$$

$$P_7(0,t) = \lambda_b \int P_6(y,t)dy \tag{22}$$

$$P_8(0,t) = \lambda_2 \int P_6(y,t)dy \tag{23}$$

$$P_9(0,t) = \lambda_2 P_5(t) \tag{24}$$

$$P_{10}(0,t) = \lambda_b P_5(t) \tag{25}$$

$$P_{12}(0,t) = \lambda_b P_{11}(t) \tag{26}$$

$$P_{13}(0,t) = \lambda_1 \int P_{12}(y,t)dy \tag{27}$$

$$P_{14}(0,t) = \lambda_a \int P_{12}(y,t)dy \tag{28}$$

$$P_{15}(0,t) = \lambda_1 P_{11}(t) \tag{29}$$

$$P_{16}(0,t) = \lambda_a P_{11}(t) \tag{30}$$

$$P_{17}(0,t) = \lambda \int P_2(x,t)dx + \lambda \int P_3(x,t)dx + \lambda \int P_6(x,t)dx + \lambda \int P_{12}(x,t)dx + \lambda P_1(t) + \lambda P_{11}(t) + \lambda P_5(t) \tag{31}$$

**Initial conditions:**  $P_1(0)$  and other state probabilities are zero.

**Solution of the model:** Taking Laplace Transform of Eq. 1-31 and on further simplification one may obtain:

$$\bar{P}_1(s) = \frac{1}{A(s)} \tag{32}$$

$$\bar{P}_2(s) = \lambda_a k_1(s) P_1(s) \tag{33}$$

$$\bar{P}_3(s) = \lambda_b k_2(s) P_1(s) \tag{34}$$

$$\bar{P}_4(s) = \lambda_a \lambda_b k_4(s) k_3(s) P_1(s) \quad (35)$$

$$\bar{P}_5(s) = \frac{\lambda_1}{(s + \lambda + \lambda_a + \lambda_b + \lambda_2 + v)} P_1(s) \quad (36)$$

$$\bar{P}_6(s) = k_6(s) P_1(s) \quad (37)$$

$$\bar{P}_7(s) = k_7(s) k_3(s) P_1(s) \quad (38)$$

$$\bar{P}_8(s) = k_8(s) k_3(s) P_1(s) \quad (39)$$

$$\bar{P}_9(s) = k_9(s) k_3(s) P_1(s) \quad (40)$$

$$\bar{P}_{10}(s) = k_{11}(s) P_1(s) \quad (41)$$

$$\bar{P}_{11}(s) = \frac{\lambda_2}{(s + \lambda + \lambda_a + \lambda_b + \lambda_1 + v)} P_1(s) \quad (42)$$

$$\bar{P}_{12}(s) = k_{12}(s) P_1(s) \quad (43)$$

$$\bar{P}_{13}(s) = k_{13}(s) k_3(s) P_1(s) \quad (44)$$

$$\bar{P}_{14}(s) = k_{14}(s) k_3(s) P_1(s) \quad (45)$$

$$\bar{P}_{15}(s) = k_{15}(s) k_3(s) P_1(s) \quad (46)$$

$$\bar{P}_{16}(s) = k_{16}(s) k_3(s) P_1(s) \quad (47)$$

$$\bar{P}_{17}(s) = k_{17}(s) k_3(s) P_1(s) \quad (48)$$

where,

$$\begin{aligned} A(s) &= (s + \lambda_a + \lambda_b + \lambda_1 + \lambda_2 + \lambda) - C_1(s) - \\ C_2(s) - C_3(s) - C_4(s) - C_5(s) - C_6(s) - C_7(s) - \\ C_8(s) - C_9(s) - C_{10}(s) - C_{11}(s) - C_{12}(s) - C_{13}(s) - C_{14}(s) \end{aligned}$$

$$k_1(s) = \frac{1 - \bar{S}_1(s + \lambda + \lambda_b)}{s + \lambda + \lambda_b}$$

$$k_2(s) = \frac{1 - \bar{S}_1(s + \lambda + \lambda_a)}{s + \lambda + \lambda_a}, k_3(s) = \frac{1 - \bar{S}_\mu(s)}{s},$$

$$k_4(s) = (k_2(s) + k_1(s))$$

$$k_5(s) = \frac{1 - \bar{S}_2(s + \lambda + \lambda_2 + \lambda_b)}{s + \lambda + \lambda_b + \lambda_2},$$

$$k_6(s) = \frac{\lambda_a \lambda_1}{(s + v + \lambda_a + \lambda_b + \lambda_2 + \lambda)} k_5(s)$$

$$k_7(s) = \lambda_b k_6(s), k_8(s) = \lambda_2 k_6(s)$$

$$k_9(s) = \frac{\lambda_2 \lambda_1}{(s + v + \lambda_a + \lambda_b + \lambda_2 + \lambda)}$$

$$k_{10}(s) = \frac{\lambda_b \lambda_1}{(s + v + \lambda_a + \lambda_b + \lambda_2 + \lambda)}$$

$$k_{11}(s) = \frac{1 - \bar{S}_2(s + \lambda + \lambda_1 + \lambda_a)}{s + \lambda + \lambda_a + \lambda_1}$$

$$k_{12}(s) = \frac{\lambda_b \lambda_2}{(s + v + \lambda_a + \lambda_b + \lambda_1 + \lambda)} k_{11}(s)$$

$$k_{13}(s) = \lambda_1 k_{12}(s), k_{14}(s) = \lambda_a k_{12}(s)$$

$$k_{15}(s) = \frac{\lambda_2 \lambda_1}{(s + v + \lambda_a + \lambda_b + \lambda_1 + \lambda)}$$

$$k_{16}(s) = \frac{\lambda_a \lambda_2}{(s + v + \lambda_a + \lambda_b + \lambda_1 + \lambda)}$$

$$k_{17}(s) = \lambda k_1(s) \lambda_a + \lambda \lambda_b k_2(s) + \lambda +$$

$$\frac{\lambda \lambda_2}{(s + v + \lambda_a + \lambda_b + \lambda_1 + \lambda)} + \frac{\lambda \lambda_1}{(s + v + \lambda_a + \lambda_b + \lambda_2 + \lambda)} + \lambda k_{12}(s) + \lambda k_6(s)$$

$$C_1(s) = \lambda_a \bar{S}_1(s + \lambda + \lambda_b),$$

$$C_2(s) = \lambda_a \lambda_b (k_2(s) + k_1(s)) \bar{S}_\mu(s)$$

$$C_3(s) = \lambda_b \bar{S}_1(s + \lambda + \lambda_a), C_4(s) = k_6(s) \lambda_2 \bar{S}_\mu(s),$$

$$C_5(s) = k_6(s) \lambda_b \bar{S}_\mu(s)$$

$$C_6(s) = \frac{\lambda_a \lambda_1}{(s + v + \lambda_a + \lambda_b + \lambda_2 + \lambda)} \bar{S}_2(s + \lambda + \lambda_2 + \lambda_b)$$

$$C_7(s) = \frac{\lambda_2 \lambda_1}{(s + v + \lambda_a + \lambda_b + \lambda_2 + \lambda)} \bar{S}_\mu(s)$$

$$C_8(s) = \frac{\lambda_b \lambda_2}{(s + v + \lambda_a + \lambda_b + \lambda_1 + \lambda)} \bar{S}_2(s + \lambda_1 + \lambda_a + \lambda)$$

$$C_9(s) = \frac{\lambda_b \lambda_1}{(s + v + \lambda_a + \lambda_b + \lambda_2 + \lambda)} \bar{S}_\mu(s)$$

$$C_{10}(s) = k_{12}(s) \lambda_1 \bar{S}_\mu(s), \quad C_{11}(s) = k_{12}(s) \lambda_a \bar{S}_\mu(s)$$

$$C_{12}(s) = \frac{\lambda_1 \lambda_2}{(s + v + \lambda_a + \lambda_b + \lambda_1 + \lambda)} \bar{S}_\mu(s)$$

$$C_{13}(s) = \frac{\lambda_a \lambda_2}{(s + v + \lambda_a + \lambda_b + \lambda_1 + \lambda)} \bar{S}_\mu(s)$$

$$C_{14}(s) = \lambda \bar{S}_\mu(s) \left( \frac{k_1(s) \lambda_a + \lambda_b k_2(s) + 1 + \frac{\lambda_2}{(s + v + \lambda_a + \lambda_b + \lambda_2 + \lambda)}}{\frac{\lambda_1}{(s + v + \lambda_a + \lambda_b + \lambda_2 + \lambda)}} + k_{12}(s) + k_6(s) \right)$$

**OPERATIONAL AVAILABILITY AND NON AVAILABILITY**

The Laplace Transform of the probabilities that the system is in operable and down state at time t, are given as follows:

$$\bar{P}_{up}(s) = \bar{P}_1(s) + \bar{P}_2(s) + \bar{P}_3(s) + \bar{P}_5(s) + \bar{P}_6(s) + \bar{P}_{11}(s) + \bar{P}_{12}(s) \quad (49)$$

$$\bar{P}_{down}(s) = \bar{P}_4(s) + \bar{P}_7(s) + \bar{P}_8(s) + \bar{P}_9(s) + \bar{P}_{10}(s) + \bar{P}_{13}(s) + \bar{P}_{14}(s) + \bar{P}_{15}(s) + \bar{P}_{16}(s) + \bar{P}_{17}(s) = P_1(s) k_3(s) \left( \frac{\lambda_a \lambda_b k_4(s) + k_7(s) + k_8(s) + k_9(s) + k_{10}(s) +}{k_{13}(s) + k_{14}(s) + k_{15}(s) + k_{16}(s) + k_{17}(s)} \right) \quad (50)$$

It is worth noticing that:

$$\bar{P}_{up}(s) + \bar{P}_{down}(s) = \frac{1}{s}$$

**Ergodic behaviour:** Using Abel's lemma is Laplace transform, viz,

$$\lim_{s \rightarrow 0} s \bar{f}(s) = \lim_{t \rightarrow \infty} f(t) = f(\text{say})$$

provided that the limit on the RHS exists, the time independent up and down state probabilities are obtained as follows:

$$\bar{P}_{up} = \frac{1}{A'(0)} \left\{ \frac{1 + \lambda_a k_1(0) + \lambda_b k_2(0) + \frac{\lambda_1}{(v + \lambda_a + \lambda_b + \lambda_2 + \lambda)} + k_6(0) + \frac{\lambda_2}{(v + \lambda_a + \lambda_b + \lambda_1 + \lambda)} + k_{12}(0)} \right\} \quad (51)$$

$$\bar{P}_{down} = \frac{M_\mu}{A'(0)} \left\{ \frac{\lambda_a \lambda_b k_4(0) + k_7(0) + k_8(0) + k_9(0) + k_{10}(0) + k_{13}(0) + k_{14}(0) + k_{15}(0) + k_{16}(0) + k_{17}(0)} \right\} \quad (52)$$

**Particular Case:** When all repairs follow exponential distribution

Setting  $\bar{S}_\mu = \frac{\mu}{s + \mu}, \quad \bar{S}_1 = \frac{\mu_i}{s + \mu_i},$  where  $I = 1, 2$

$$\bar{P}_1(s) = \frac{1}{g_1(s)} \quad (53)$$

$$\bar{P}_2(s) = g_2(s) P_1(s) \quad (54)$$

$$\bar{P}_3(s) = g_3(s) P_1(s) \quad (55)$$

$$\bar{P}_4(s) = g_4(s) P_1(s) \quad (56)$$

$$\bar{P}_5(s) = g_5(s) P_1(s) \quad (57)$$

$$\bar{P}_6(s) = g_6(s) P_1(s) \quad (58)$$

$$\bar{P}_7(s) = g_7(s) P_1(s) \quad (59)$$

$$\bar{P}_8(s) = g_8(s) P_1(s) \quad (60)$$

$$\overline{P}_9(s) = g_9(s)P_1(s) \tag{61}$$

$$\overline{P}_{10}(s) = g_{10}(s)P_1(s) \tag{62}$$

$$\overline{P}_{11}(s) = g_{11}(s)P_1(s) \tag{63}$$

$$\overline{P}_{12}(s) = g_{12}(s)P_1(s) \tag{64}$$

$$\overline{P}_{13}(s) = g_{13}(s)P_1(s) \tag{65}$$

$$\overline{P}_{14}(s) = g_{14}(s)P_1(s) \tag{66}$$

$$\overline{P}_{15}(s) = g_{15}(s)P_1(s) \tag{67}$$

$$\overline{P}_{16}(s) = g_{16}(s)P_1(s) \tag{68}$$

$$\overline{P}_{17}(s) = g_{17}(s)P_1(s) \tag{69}$$

$$g_{11}(s) = \frac{\lambda_2}{s + \lambda + \lambda_b + \lambda_a + \lambda_1 + v}$$

$$g_{12}(s) = \frac{\lambda_2 \lambda_b}{(s + \lambda + \lambda_b + \lambda_a + \lambda_1 + v)(s + \lambda + \lambda_1 + \lambda_a + \mu_2)}$$

$$g_{13}(s) = \frac{\lambda_1 \lambda_2 \lambda_b}{(s + \lambda + \lambda_b + \lambda_a + \lambda_1 + v)(s + \lambda + \lambda_1 + \lambda_a + \mu_2)(s + \mu)}$$

$$g_{14}(s) = \frac{\lambda_a \lambda_2 \lambda_b}{(s + \lambda + \lambda_b + \lambda_a + \lambda_1 + v)(s + \lambda + \lambda_1 + \lambda_a + \mu_2)(s + \mu)}$$

$$g_{15}(s) = \frac{\lambda_1 \lambda_2}{(s + \lambda + \lambda_b + \lambda_a + \lambda_1 + v)(s + \mu)}$$

$$g_{16}(s) = \frac{\lambda_a \lambda_2}{(s + \lambda + \lambda_b + \lambda_a + \lambda_1 + v)(s + \mu)}$$

$$g_{17}(s) = \frac{\lambda}{(s + \mu)} \left\{ \frac{g_2(s) + g_3(s) + g_5(s)}{g_6(s) + g_{11}(s) + g_{12}(s)} \right\}$$

where,

$$g_1(s) = (s + \lambda_a + \lambda_b + \lambda_1 + \lambda_2 + \lambda) - \mu_1(g_2(s) + g_3(s)) - \mu(g_4(s) + g_8(s) + g_7(s) + g_8(s) + g_9(s) + g_{10}(s) + g_{13}(s) + g_{14}(s) + g_{15}(s) + g_{16}(s) + g_{17}(s)) - \mu_2(g_6(s) + g_{12}(s))$$

$$g_2(s) = \frac{\lambda_a}{s + \lambda + \lambda_b + \mu_1}, \quad g_3(s) = \frac{\lambda_b}{s + \lambda + \lambda_a + \mu_1}$$

$$g_4(s) = \lambda_a \lambda_b \left( \frac{1}{(s + \lambda + \lambda_a + \mu_1)} + \frac{1}{(s + \lambda + \lambda_b + \mu_1)} \right) \frac{1}{s + \mu}$$

$$g_5(s) = \frac{\lambda_1}{s + \lambda + \lambda_b + \lambda_a + \lambda_2 + v}$$

$$g_6(s) = \frac{\lambda_1 \lambda_a}{(s + \lambda + \lambda_b + \lambda_a + \lambda_2 + v)(s + \lambda + \lambda_2 + \lambda_b + \mu_2)}$$

$$g_7(s) = \frac{\lambda_1 \lambda_a \lambda_b}{(s + \lambda + \lambda_b + \lambda_a + \lambda_2 + v)(s + \lambda + \lambda_2 + \lambda_b + \mu_2)(s + \mu)}$$

$$g_8(s) = \frac{\lambda_1 \lambda_a \lambda_2}{(s + \lambda + \lambda_b + \lambda_a + \lambda_2 + v)(s + \lambda + \lambda_2 + \lambda_b + \mu_2)(s + \mu)}$$

$$g_9(s) = \frac{\lambda_1 \lambda_2}{(s + \lambda + \lambda_b + \lambda_a + \lambda_2 + v)(s + \mu)}$$

$$g_{10}(s) = \frac{\lambda_1 \lambda_b}{(s + \lambda + \lambda_b + \lambda_a + \lambda_2 + v)(s + \mu)}$$

### OPERATIONAL AVAILABILITY AND NON AVAILABILITY

The Laplace Transform of the probabilities that the system is in operable and down state at time t, are given as follows:

$$\begin{aligned} \overline{P}_{up}(s) &= \overline{P}_1(s) + \overline{P}_2(s) + \overline{P}_3(s) + \overline{P}_5(s) + \overline{P}_6(s) + \overline{P}_{11}(s) + \overline{P}_{12}(s) \\ &= \overline{P}_1(s) \left\{ 1 + g_2(s) + g_3(s) + g_5(s) + \frac{g_6(s) + g_{11}(s) + g_{12}(s)}{g_6(s) + g_{11}(s) + g_{12}(s)} \right\} \end{aligned} \tag{70}$$

$$\overline{P}_{down}(s) = 1 - \overline{P}_{up}(s) \tag{71}$$

**Reliability:** The reliability is given by:

$$R(t) = m_1 e^{-q_1 t} + m_2 e^{-q_2 t} + m_3 e^{-q_3 t} + m_5 e^{-q_5 t} + m_7 e^{-q_7 t} \tag{72}$$

where,

$$q_1 = \lambda_a + \lambda_b + \lambda_1 + \lambda_2 + \lambda, \quad q_2 = \lambda_b + \lambda, \quad q_3 = \lambda_a + \lambda$$

$$q_5 = \lambda_b + \lambda_2 + \lambda, \quad q_7 = \lambda_a + \lambda_1 + \lambda$$

$$m_1 = m_8 + m_9 - 1 - m_2 - m_3$$

$$m_2 = \frac{\lambda_a}{\lambda_a + \lambda_1 + \lambda_2}, m_3 = \frac{\lambda_b}{\lambda_b + \lambda_1 + \lambda_2}, m_5 = \frac{\lambda_1}{\lambda_a + \lambda_1},$$

$$m_7 = \frac{\lambda_2}{\lambda_b + \lambda_2} m_8 = \frac{\lambda_a}{\lambda_a + \lambda_1}, m_9 = \frac{\lambda_b}{\lambda_b + \lambda_2}$$

**MTTF:** The mean time to system failure is given by:

$$MTTF = \int_0^\infty R(t)dt = \frac{m_1}{q_1} + \frac{m_2}{q_2} + \frac{m_3}{q_3} + \frac{m_5}{q_5} + \frac{m_7}{q_7} \quad (73)$$

**NUMERICAL ILLUSTRATIONS**

**Analysis of availability:** Setting

$$\lambda_a = 0.001, \lambda_b = 0.002, \lambda_1 = 0.001,$$

$$\lambda_2 = 0.002, \lambda = 0.009,$$

$$v = 0.95, \mu_1 = 0.92, \mu_2 = 0.86$$

in the Eq. 70 and then taking the inverse Laplace transform, the operational availability is obtained as:

$$P_{up}(t) = z_1 e^{-n_1 t} + z_2 e^{-n_2 t} + z_3 e^{-n_3 t} + z_4 e^{-n_4 t} + z_5 e^{-n_5 t} + z_6 e^{-n_6 t} + z_7 e^{-n_7 t} \quad (74)$$

where

$$n_1 = \lambda_a + \lambda_b + \lambda_1 + \lambda_2 + \lambda, n_2 = \lambda_b + \lambda + \mu_1(x),$$

$$n_3 = \lambda_a + \lambda + \mu_1(x)$$

$$n_4 = \lambda_a + \lambda_b + \lambda_2 + \lambda + v, n_5 = \lambda_b + \lambda + \lambda_2 + \mu_2(y)$$

$$n_6 = \lambda_a + \lambda_b + \lambda_1 + \lambda + v, n_7 = \lambda_a + \lambda + \lambda_1 + \mu_2(y)$$

$$z_1 = 1 - \frac{\lambda_a}{n_1 - n_2} - \frac{\lambda_b}{n_1 - n_3} - \frac{\lambda_1}{n_1 - n_4} + \frac{\lambda_a \lambda_1}{(n_4 - n_1)(n_5 - n_1)} - \frac{\lambda_2}{n_1 - n_6} + \frac{\lambda_b \lambda_2}{(n_6 - n_1)(n_7 - n_1)}$$

$$z_2 = \frac{\lambda_a}{n_1 - n_2}, z_3 = \frac{\lambda_b}{n_1 - n_3},$$

$$z_3 = \frac{\lambda_1}{n_1 - n_4} + \frac{\lambda_a \lambda_1}{(n_1 - n_4)(n_5 - n_4)}$$

$$z_5 = \frac{\lambda_a \lambda_1}{(n_4 - n_5)(n_1 - n_5)}, z_6 = \frac{\lambda_2}{n_1 - n_6} + \frac{\lambda_b \lambda_2}{(n_7 - n_6)(n_1 - n_6)}$$

$$z_7 = \frac{\lambda_b \lambda_2}{(n_6 - n_7)(n_1 - n_7)}$$

Substituting different values of *t* is equation (74) one may obtain Table 1 and Fig. 1.

**Reliability analysis:** Setting  $\lambda_a = 0.001, \lambda_b = 0.002, \lambda_1 = 0.011, \lambda_2 = 0.015, \lambda = 0.05$  in the Eq. 72 one may obtain the variations in reliability of the system with time as shown in Table 2 and Fig. 2.

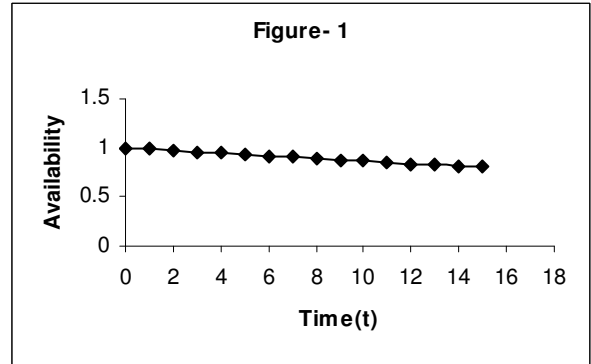


Fig. 1: Availability v/s Time

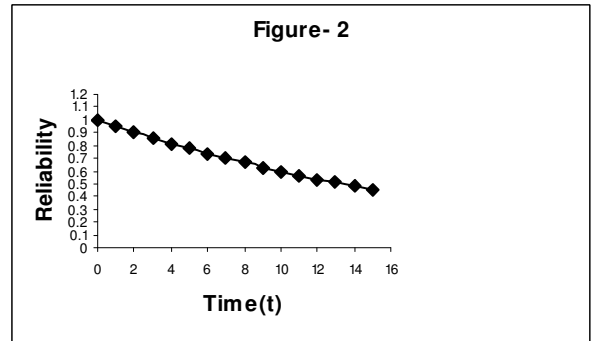


Fig. 2: Reliability v/s Time

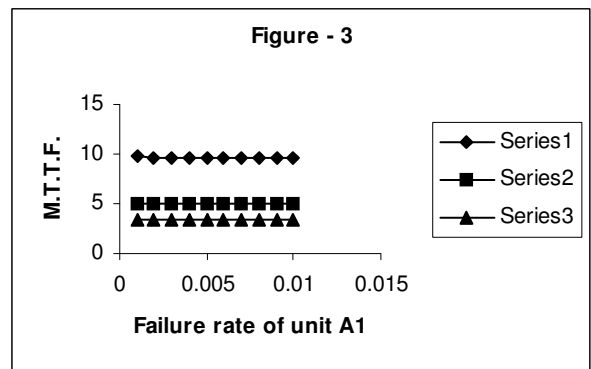


Fig. 3: M.T.T.F. v/s Failure rate of unit A1

Table 1: Variation of availability with time

Time (t)	Availability [Pup (t)]
0	0.999982
1	0.988951
2	0.975725
3	0.96178
4	0.947687
5	0.933666
6	0.9198
7	0.906119
8	0.892634
9	0.879346
10	0.866255
11	0.853359
12	0.840654
13	0.828138
14	0.815809
15	0.803663

Table 2: Variation of reliability with time

Time (t)	Reliability[R (t)]
0	1
1	0.951056
2	0.904185
3	0.859332
4	0.816437
5	0.77544
6	0.736279
7	0.698895
8	0.663224
9	0.629205
10	0.596777
11	0.565881
12	0.536456
13	0.508444
14	0.481789
15	0.456433

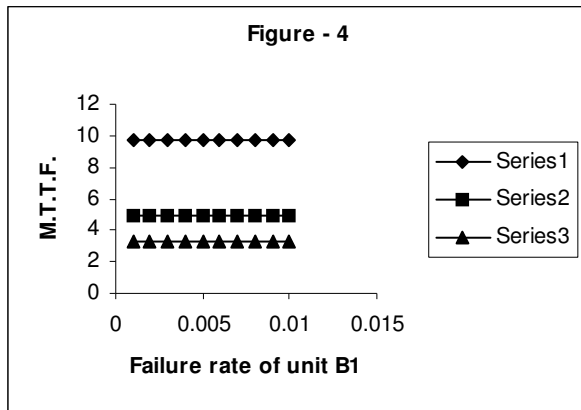


Fig. 4: M.T.T.F. v/s Failure rate of unit B1

Table 3: Variation of M. T. T. F. with failure rate of A<sub>1</sub> unit

M.T.T.F.			
0.001	9.712430	4.955933	3.319280
0.002	9.699658	4.953789	3.318573
0.003	9.687316	4.951683	3.317875

0.004	9.675385	4.949614	3.317185
0.005	9.66385	4.947581	3.316503
0.006	9.652699	4.94585	3.31583
0.007	9.641916	4.943624	3.315165
0.008	9.63149	4.941698	3.314507
0.009	9.621406	4.939805	3.313858
0.001	9.712430	4.955933	3.319280

**MTTF analysis:**

- Setting the values  $\lambda_2 = 0.02, \lambda_1 = 0.01, \lambda_b = 0.002$  and taking different values of  $\lambda_a$  in the Eq. 73 one may obtain the variations of MTTF of the system against the failure rate of unit A<sub>1</sub>, ( $\lambda_a$ ) as shown in Table 3 and Fig. 3.
- Setting the values  $\lambda_2 = 0.02, \lambda_1 = 0.01, \lambda_a = 0.001$  and taking different values of  $\lambda_b$  in the Eq. 73 one may obtain the variations of M.T.T.F. of the system against the failure rate of unit B<sub>1</sub> ( $\lambda_b$ ) as shown in Table 4 and Fig. 4.
- Setting the values  $\lambda_2 = 0.02, \lambda_a = 0.001, \lambda_b = 0.002$  and taking different values of  $\lambda$  in the Eq. 73 one may

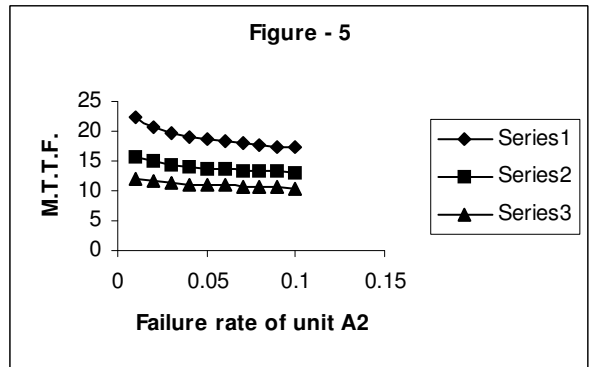


Fig. 5: M.T.T.F. v/s Failure rate of unit A2

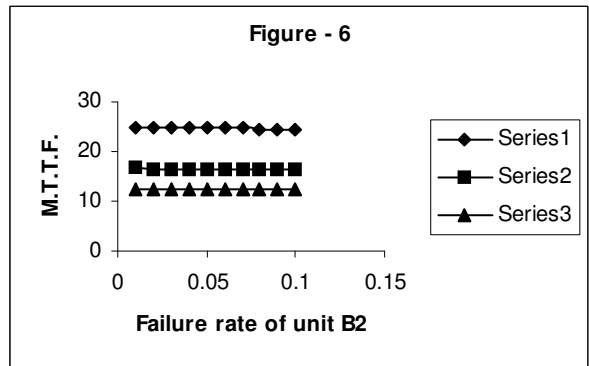


Fig. 6: M.T.T.F. v/s Failure rate of unit B2

Table 4: Variation of M. T. T. F. with failure rate of B<sub>1</sub> unit

M.T.T.F.			
0.001	9.716869	4.956836	3.319596
0.002	9.71243	4.955933	3.31928
0.003	9.708154	4.955048	3.318968
0.004	9.704035	4.954179	3.318661
0.005	9.700066	4.953325	3.318357
0.006	9.696241	4.952488	3.318056
0.007	9.692557	4.951665	3.31776
0.008	9.689009	4.950858	3.317467
0.009	9.68559	4.950065	3.317177
0.01	9.682298	4.949286	3.316892

0.07	24.600948	16.514713	12.425385
0.08	24.58382	16.506235	12.420496
0.09	24.569265	16.498861	12.416171
0.1	24.556746	16.492395	12.412319

- Setting the values  $\lambda_1 = 0.01$ ,  $\lambda_a = 0.001$ ,  $\lambda_b = 0.002$  and taking different values of  $\lambda$  in the Eq. 73 one may obtain the variations of MTTF of the system against the failure rate of unit B<sub>2</sub> ( $\lambda_2$ ) as shown in Table 6 and Fig. 6.

CONCLUSION

The concept of redundancy of the generating unit can be applied to the areas where the electricity requirements are increasing at an alarming rate. The findings in Table 1 and 2 depicts that the system is available and reliable for a longer time period. The failures are considered to occur purely by chance for a component which is operating within its useful life period. So, under these conditions the calculations shown in Table 3-6 shows apparently that the failure rate is the reciprocal of the mean time to system failure (MTTF).

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NOTATIONS

- $\lambda_i, v$ : Failure and constant repair rate of unit A<sub>2</sub> or B<sub>2</sub> (i = 1, 2).
- $\lambda_j, \mu_1(x)$ : Failure and repair rate of unit A<sub>2</sub> or B<sub>1</sub> (j = a, b).
- $\lambda$ : Failure rate of subsystem C.
- $\mu(z)$ : Repair rate when the system is in failed state.
- $\mu_2(y)$ : Repair rate of both units of subsystem A or subsystem B.
- $P_1(t)$ : Probability that the system is in operable state at time t.
- $P_i(x, t)\Delta$ : Probability that the system is in degraded state at time t and elapsed repair time lies between x and x +  $\Delta$ , where  $9i = 2, 3$
- $P_j(y, t)\Delta$ : Probability that the system is in degraded state at time t and elapsed repair time lies between y and y +  $\Delta$ , where (j = 6, 12)

obtain the variations of MTTF of the system against the failure rate of unit A<sub>1</sub> ( $\lambda_a$ ) as shown in Table 5 and Fig. 5.

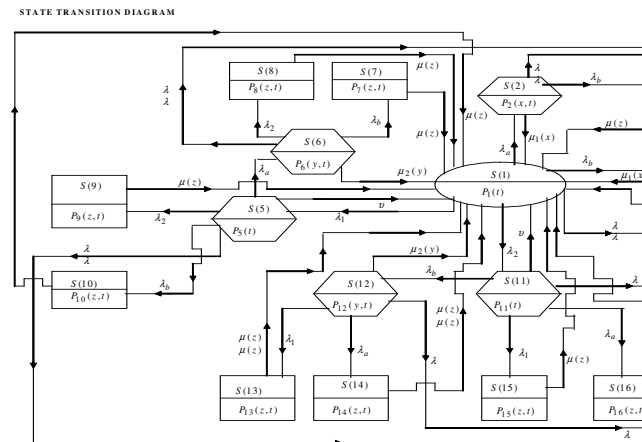


Fig. 7: STATE TRANSITION DIAGRAM

Table 6: Variation of M. T. T. F. with failure rate of B<sub>2</sub> unit

M.T.T.F.			
0.01	24.839481	16.614389	12.47681
0.02	24.768173	16.587769	12.464078
0.03	24.716404	16.566874	12.453601
0.04	24.677107	16.550035	12.444826
0.05	24.646261	16.536179	12.437371
0.06	24.621405	16.524572	12.430959






$P_k(z, t)\Delta$ : Probability that the system is in failed state at time  $t$  and elapsed repair time lies between  $z$  and  $z + \Delta$ , where ( $k = 4, 7, 8, 9, 10, 13, 14, 15, 16, 17$ )

$P_m(t)$ : Probability that the system is in degraded state at time  $t$  where ( $m = 5, 11$ )

$$\int_0^{\infty}$$

Otherwise stated.

: Operable    : Degraded    : Failed

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